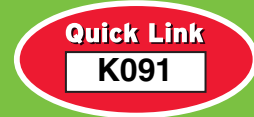


Servos SmartStep



Cost-Effective Servo Capability with Stepper Simplicity

Easily migrate from steppers to the higher precision of servos in minutes with Omron's SmartStep servo drivers and ultra-compact 3-phase servo motors. They accept pulse-train input that can be configured quickly via simple DIP switches and have an on-line auto-tuning function. SmartStep offers all the simplicity and cost-effectiveness of a stepper with the added advantages of the servo drive capability.

Motor Features

- Sizes 30 W to 750 W, rated speed 3,000 rpm
- Accepts incremental encoder input at 2,000 p/r
- Cylindrical and flat type servo motors available
- Peak torque up to three times continuous torque during 3 seconds
- Easy to install with pre-built cables
- Motors with brake are available

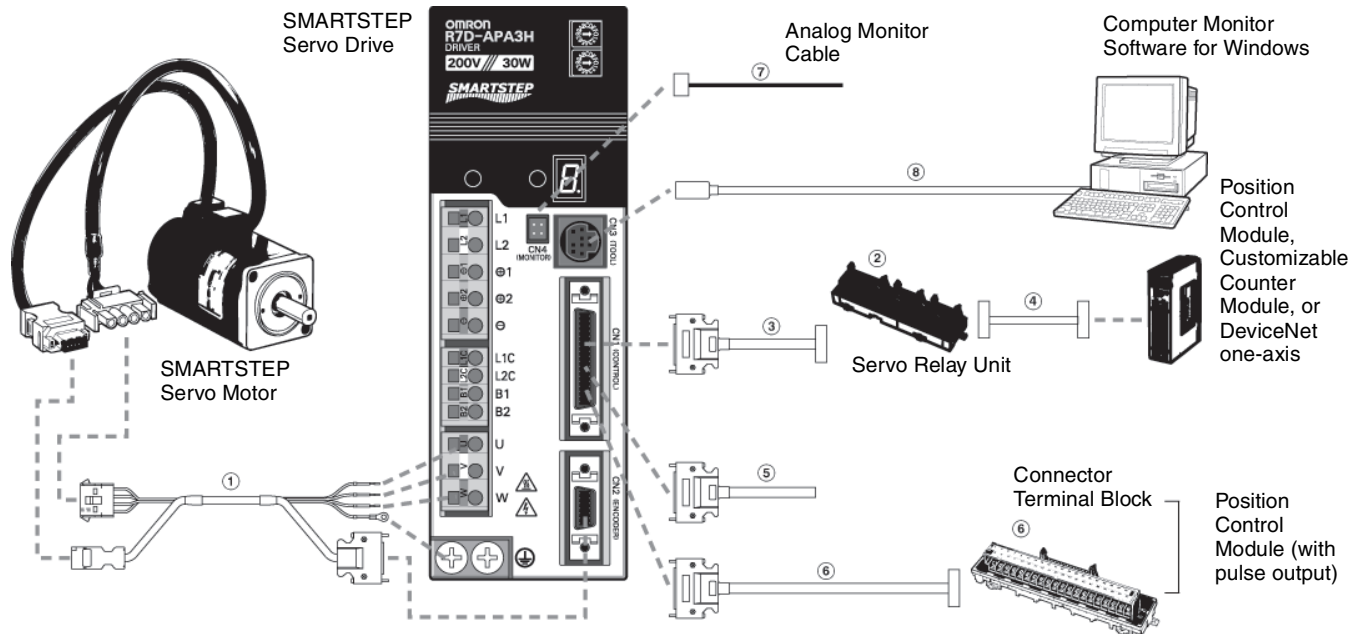
Driver Features

- Output range from 30 W to 750 W
- 300% peak current over nominal
- Control via pulse train (speed and position)



- Four position resolution settings:
 - 500 pulses/rotation (0.72°/step)
 - 1,000 pulses/rotation (0.36°/step)
 - 5,000 pulses/rotation (0.072°/step)
 - 10,000 pulses/rotation (0.036°/step)
- SmartStep does not require the use of PC configuration software, making setup as easy as using a stepper motor for basic capabilities
- To optimize performance, use PC software for on-line auto-tuning of values and monitoring

Ordering Information



Add cable length to the part number in place of □□□: 003 for 3 m cable, 005 for 5 m, 010 for 10 m, 015 for 15 m and 020 for 20 m.

Note: Circled numbers refer to the configuration diagram on page I-8.

SmartStep Servos

| Wattage | Servo motor model | Servo drive model | ① Power cable/Encoder cable model (Add cable length for □□□) |
|---|-------------------|-------------------|---|
| Cylindrical Servo Motors 100 VAC Without Brake, Shaft Without Keyway | | | |
| 30 W | R7M-A03030-S1 | R7D-APA3L | R7A-CEA□□□S |
| 50 W | R7M-A05030-S1 | R7D-APA5L | R7A-CEA□□□S |
| 100 W | R7M-A10030-S1 | R7D-AP01L | R7A-CEA□□□S |
| 200 W | R7M-A20030-S1 | R7D-AP02L | R7A-CEA□□□S |
| 400 W | R7M-A40030-S1 | R7D-AP04L | R7A-CEA□□□S |
| Cylindrical Servo Motors 100 VAC With Brake, Shaft With Keyway | | | |
| 30 W | R7M-A03030-BS1 | R7D-APA3L | R7A-CEA□□□B |
| 50 W | R7M-A05030-BS1 | R7D-APA5L | R7A-CEA□□□B |
| 100 W | R7M-A10030-BS1 | R7D-AP01L | R7A-CEA□□□B |
| 200 W | R7M-A20030-BS1 | R7D-AP02L | R7A-CEA□□□B |
| 400 W | R7M-A40030-BS1 | R7D-AP04L | R7A-CEA□□□B |
| Cylindrical Servo Motors 200 VAC Without Brake, Shaft With Keyway | | | |
| 30 W | R7M-A03030-S1 | R7D-APA3H | R7A-CEA□□□S |
| 50 W | R7M-A05030-S1 | R7D-APA5H | R7A-CEA□□□S |
| 100 W | R7M-A10030-S1 | R7D-AP01H | R7A-CEA□□□S |
| 200 W | R7M-A20030-S1 | R7D-AP02H | R7A-CEA□□□S |
| 400 W | R7M-A40030-S1 | R7D-AP04H | R7A-CEA□□□S |
| 750 W | R7M-A75030-S1 | R7D-AP08H | R7A-CEA□□□S |
| Cylindrical Servo Motors 200 VAC With Brake, Shaft With Keyway | | | |
| 30 W | R7M-A03030-BS1 | R7D-APA3H | R7A-CEA□□□B |
| 50 W | R7M-A05030-BS1 | R7D-APA5H | R7A-CEA□□□B |
| 100 W | R7M-A10030-BS1 | R7D-AP01H | R7A-CEA□□□B |
| 200 W | R7M-A20030-BS1 | R7D-AP02H | R7A-CEA□□□B |
| 400 W | R7M-A40030-BS1 | R7D-AP04H | R7A-CEA□□□B |
| 750 W | R7M-A75030-BS1 | R7D-AP08H | R7A-CEA□□□B |
| Flat Servo Motors 100 VAC Without Brake, Shaft With Keyway | | | |
| 100 W | R7M-AP10030-S1 | R7D-AP01L | R7A-CEA□□□S |
| 200 W | R7M-AP20030-S1 | R7D-AP02L | R7A-CEA□□□S |
| 400 W | R7M-AP40030-S1 | R7D-AP04L | R7A-CEA□□□S |
| Flat Servo Motors 100 VAC With Brake, Shaft With Keyway | | | |
| 100 W | R7M-AP10030-BS1 | R7D-AP01L | R7A-CEA□□□B |
| 200 W | R7M-AP20030-BS1 | R7D-AP02L | R7A-CEA□□□B |
| 400 W | R7M-AP40030-BS1 | R7D-AP04L | R7A-CEA□□□B |
| Flat Servo Motors 200 VAC Without Brake, Shaft With Keyway | | | |
| 100 W | R7M-AP10030-S1 | R7D-AP01H | R7A-CEA□□□S |
| 200 W | R7M-AP20030-S1 | R7D-AP02H | R7A-CEA□□□S |
| 400 W | R7M-AP40030-S1 | R7D-AP04H | R7A-CEA□□□S |
| 750 W | R7M-AP75030-S1 | R7D-AP08H | R7A-CEA□□□S |
| Flat Servo Motors 200 VAC With Brake, Shaft With Keyway | | | |
| 100 W | R7M-AP10030-BS1 | R7D-AP01H | R7A-CEA□□□B |
| 200 W | R7M-AP20030-BS1 | R7D-AP02H | R7A-CEA□□□B |
| 400 W | R7M-AP40030-BS1 | R7D-AP04H | R7A-CEA□□□B |
| 750 W | R7M-AP75030-BS1 | R7D-AP08H | R7A-CEA□□□B |

Cables and Accessories

| Description | Devices connected | Specification | Model |
|---|--|----------------------------|---------------|
| ② Servo relay units connect cables from PLC position controller and servo drive | CS1W-NC113/133, CJ1W-NC113/133; 1 axis; does not support communications functions | — | XW2B-20J6-1B |
| | CS1W-NC213/233/413/433, CJ1W-NC213/233/413/433; 2 axes; does not support communications functions | — | XW2B-40J6-2B |
| | CQM1H-PLB21 and CQM1-CPU43-V1; 1 axis; does not support communications functions | — | XW2B-20J6-3B |
| | CS1W-NC213/233/413/433, CJ1W-NC213/233/413/433; 2 axes; supports communications functions | — | XW2B-40J6-4A |
| | CJ1M-CPU22/23; 1 axis; does not support communications functions | — | XW2B-20J6-8A |
| | CJ1M-CPU22/23; 2 axes; does not support communications functions | — | XW2B-40J6-9A |
| ③ Universal terminal block cable to servo drive | Doesn't support communications functions. (For the XW2B-□□J6-□B) | 1 m length | XW2Z-100J-B5 |
| | | 2 m length | XW2Z-200J-B5 |
| ④ Position controller PLC module cable | CQM1H-PLB21 and CQM1-CPU43-V1 to XW2B-20J6-3B servo relay unit | 1 m length | XW2Z-100J-A3 |
| | CJ1W-NC113 to XW2B-20J6-1B servo relay unit | 1 m length | XW2Z-100J-A16 |
| | CJ1W-NC213 or CJ1W-NC413 to XW2B-20J6-2B servo relay unit | 1 m length | XW2Z-100J-A17 |
| | CJ1W-NC133 to XW2B-20J6-1B servo relay unit | 1 m length | XW2Z-100J-A20 |
| | CJ1W-NC233 or CJ1W-NC433 to XW2B-40J6-2B servo relay unit | 1 m length | XW2Z-100J-A21 |
| | CJ1M-CPU22 or CJ1M-CPU23 to XW2B-20J6-8A (1 axis) or XW2B-40J6-9A (2 axes) servo relay unit | 1 m length | XW2Z-100J-A26 |
| | CS1W-NC113 to XW2B-20J6-1B servo relay unit | 1 m length | XW2Z-100J-A8 |
| | CS1W-NC213 or CS1W-NC413 to XW2B-40J6-2B servo relay unit | 1 m length | XW2Z-100J-A9 |
| | CS1W-NC133 to XW2B-20J6-B1 servo relay unit | 1 m length | XW2Z-100J-A12 |
| | CS1W-NC233 or CS1W-NC433 to XW2B-40J6-2B servo relay unit | 1 m length | XW2Z-100J-A13 |
| ⑤ Control cable | For general-purpose Controllers (mating connector for CJ1 on one end, open ended on the other end) | 1 m length | R88A-CPU001S |
| | | 2 m length | R88A-CPU002S |
| ⑥ Universal terminal block | For position control modules with pulse output and general-purpose controllers | — | XW2B-40F5-P |
| | Connector cable between terminal block and servo driver | 1 m length | R88A-CTU001N |
| | | 2 m length | R88A-CTU002N |
| ⑦ Analog monitor cable (port CN4) | Servo drive to PC | 1 m length | R88A-CMW001S |
| ⑧ Computer monitor cable (port CN3) | Servo drive to PC | 2 m length | R7A-CCA002P2 |
| Filters | For servo drive R7D-APA3H, APA5H, AP01H, AP02H; R7D-APA3L, APA5L, AP01L, AP02L | 4 A, 250 VAC single phase | R88A-FIW104-E |
| | For servo drive R7D-AP04H, AP04L | 7 A, 250 VAC single phase | R88A-FIW107-E |
| | For servo drive R7D-AP08H | 15 A, 250 VAC single phase | R88A-FIW115-E |
| Control I/O connector (CN1) | — | — | R88A-CNU01C |
| SmartStep encoder connector (CN2) | — | — | R7A-CNA01R |
| External regeneration resistor | — | 200 W, 47 Ω | R88A-RR22047S |
| Parameter copy unit with cable | — | — | R7A-PR02A |
| Configuration and monitoring software | For servo drives and inverters | Version 1.11 or higher | CX-DRIVE |
| Complete OMRON software suite | Includes CX-Drive | — | CX-ONE |

Specifications

Servo Drives General Specifications

| Item | Specification |
|------------------------------|---|
| Operating ambient | 0° to 55° C (32° F to 131° F), 90% RH max. (with no condensation) |
| Storage ambient | -20° to 85° C (-4° F to 185° F), 90% RH max. (with no condensation) |
| Storage/operating atmosphere | No corrosive gases. |
| Vibration resistance | 10 to 55 Hz in X, Y, and Z directions with 0.1-mm double amplitude or acceleration of 4.9 m/s ² max., whichever is smaller |
| Impact resistance | Acceleration 19.6 m/s ² max., in X, Y, and Z directions, three times |
| Insulation resistance | Between power line terminals and case: 0.5 MΩ min. (at 500 VDC) |
| Dielectric strength | Between power line terminals and case: 1,500 VAC for 1 min. at 50/60 Hz between each control signal and case: 500 VAC for 1 min. |
| Protective structure | Built into panel (IP10). |
| International standards | Approval obtained for UL, cUL, and EN (EMC directive and low-voltage directive) |

Servo Drives Performance Specifications

100 VAC Input Models

| Item | Specification | | | | |
|--|--|------------|------------|------------|------------|
| Model | R7D-APA3L | R7D-APA5L | R7D-AP01L | R7D-AP02L | R7D-AP04L |
| Rated output | 30 W | 50 W | 100 W | 200 W | 400 W |
| Continuous output current (rms) | 0.42 | 0.6 | 0.89 | 2.0 | 2.6 |
| Momentary maximum output current (rms) | 1.3 | 1.9 | 2.8 | 6.0 | 8.0 |
| Control power supply | Single-phase 100/115 VAC (85 to 127 V) 50/60 Hz | | | | |
| Main-circuit power supply | Single-phase 100/115 VAC (85 to 127 V) 50/60 Hz (Voltage doubler method) | | | | |
| Control method | All-digital servo | | | | |
| Speed feedback | 2,000 pulses/revolution Incremental Encoder | | | | |
| Inverter method | PWM method based on IGBT | | | | |
| PWM frequency | 11.7 kHz | | | | |
| Weight [kg (lb)] | 0.8 (1.76) | 0.8 (1.76) | 0.8 (1.76) | 0.8 (1.76) | 1.1 (2.43) |
| Compatible motor voltage | 200 V | | | | |
| Compatible motor capacity | 30 W | 50 W | 100 W | 200 W | 400 W |
| Command pulse response | 250 kHz | | | | |
| Applicable servo motor (R7M-) | A03030_ | A05030_ | A10030_ | A20030_ | A40030_ |
| | — | — | AP10030_ | AP20030_ | AP40030_ |

200 VAC Input Models

| Item | Specification | | | | | |
|--|--|------------|------------|------------|------------|------------|
| Model | R7D-APA3H | R7D-APA5H | R7D-AP01H | R7D-AP02H | R7D-AP04H | R7D-AP08H |
| Rated output | 30 W | 50 W | 100 W | 200 W | 400 W | 750 W |
| Continuous output current (rms) | 0.42 | 0.6 | 0.89 | 2.0 | 2.6 | 4.4 |
| Momentary maximum output current (rms) | 1.3 | 1.9 | 2.8 | 6.0 | 8.0 | 13.9 |
| Control power supply | Single-phase 200/230 VAC (170 to 253 V) 50/60 Hz | | | | | |
| Main-circuit power supply | Single-phase 200/230 VAC (170 to 253 V) 50/60 Hz (Three-phase 200/230 VAC can be used with the 750 W model) | | | | | |
| Control method | All-digital servo | | | | | |
| Speed feedback | 2,000 pulses/revolution incremental encoder | | | | | |
| Inverter method | PWM method based on IGBT | | | | | |
| PWM frequency | 11.7 kHz | | | | | |
| Weight [kg (lb)] | 0.8 (1.76) | 0.8 (1.76) | 0.8 (1.76) | 0.8 (1.76) | 1.1 (2.43) | 1.7 (3.75) |
| Servo motor voltage | 200 V | | | | | |
| Servo motor capacity | 30 W | 50 W | 100 W | 200 W | 400 W | 750 W |
| Command pulse response | 250 kHz | | | | | |
| Applicable servo motor (R7M-) | A03030 | A05030 | A10030 | A20030 | A40030 | A75030 |
| | — | — | AP10030 | AP20030 | AP40030 | AP75030 |

Servo Motor General Specifications

| Item | Specification |
|------------------------------|---|
| Operating ambient | 0° C to 40° C (32° F to 104° F), 20% to 80% RH (with no condensation) |
| Storage ambient | -20° C to 60° C (-4° F to 140° F), 20% to 80% RH (with no condensation) |
| Storage/operating atmosphere | No corrosive gases |
| Vibration resistance | 10 to 2,500 Hz in X, Y, and Z directions with 0.2 mm double amplitude or acceleration of 24.5 m/s ² max., whichever is smaller |
| Impact resistance | Acceleration 98 m/s ² max., in a vertical direction, two times |
| Insulation resistance | Between power line terminals and FG: 10 MΩ min. (at 500 VDC) |
| Dielectric strength | Between power line terminals and FG: 1,500 V AC for 1 min at 50/60 Hz |
| Run position | Any direction |
| Insulation grade | Type B |
| Structure | Totally-enclosed self-cooling |
| Protective structure | IP55 for both the cylindrical and flat servo motors |
| Vibration grade | V-15 |
| Mounting method | Flange-mounting |
| International standards | Approval obtained for UL, cUL, and EN (EMC directive and low-voltage directive) |

Servo Motor Performance Specifications

Flat Servo Motors without Brakes

| Item | R7M-AP10030-S1 | R7M-AP20030-S1 | R7M-AP40030-S1 | R7M-AP75030-S1 |
|----------------------------------|---|---|---|---|
| Rated output | 100 W | 200 W | 400 W | 750 W |
| Rated torque | 0.318 N•m | 0.637 N•m | 1.27 N•m | 2.39 N•m |
| Rated rotation speed | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. |
| Momentary maximum rotation speed | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. |
| Momentary maximum torque | 0.96 N•m | 1.91 N•m | 3.82 N•m | 7.1 N•m |
| Rated current | 0.89 A (rms) | 2.0 A (rms) | 2.6 A (rms) | 4.1 A (rms) |
| Momentary maximum current | 2.8 A (rms) | 6.0 A (rms) | 8.0 A (rms) | 13.9 A (rms) |
| Rotor inertia | 6.5 × 10 ⁻⁶ kg•m ² | 2.09 × 10 ⁻⁵ kg•m ² | 3.47 × 10 ⁻⁵ kg•m ² | 2.11 × 10 ⁻⁴ kg•m ² |
| Power rate | 15.7 kW/s | 19.4 kW/s | 46.8 kW/s | 26.9 kW/s |
| Allowable radial load | 78 N | 245 N | 245 N | 392 N |
| Allowable thrust load | 49 N | 68 N | 68 N | 147 N |
| Weight (without brake -S1) | 0.7 kg | 1.4 kg | 2.1 kg | 4.2 kg |
| Applicable servo driver | R7D-AP01H/L | R7D-AP02H/L | R7D-AP04H/L | R7D-AP08H |
| Encoder resolution | 2,000 pulses/revolution for phase-A and phase-B, 1 pulse/revolution for phase-Z | | | |
| Radiation shield dimensions | t6 x250 mm square | | | t12 x300 mm square |

Flat Servo Motors with Brakes

| Item | R7M-AP10030-BS1 | R7M-AP20030-BS1 | R7M-AP40030-BS1 | R7M-AP75030-BS1 | |
|----------------------------------|---|---|---|---|---|
| Rated output | 100 W | 200 W | 400 W | 750 W | |
| Rated torque | 0.318 N•m | 0.637 N•m | 1.27 N•m | 2.39 N•m | |
| Rated rotation speed | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. | |
| Momentary maximum rotation speed | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. | |
| Momentary maximum torque | 0.96 N•m | 1.91 N•m | 3.82 N•m | 7.1 N•m | |
| Rated current | 0.89 A (rms) | 2.0 A (rms) | 2.6 A (rms) | 4.1 A (rms) | |
| Momentary maximum current | 2.8 A (rms) | 6.0 A (rms) | 8.0 A (rms) | 13.9 A (rms) | |
| Rotor inertia | 6.5 × 10 ⁻⁶ kg•m ² | 2.09 × 10 ⁻⁵ kg•m ² | 3.47 × 10 ⁻⁵ kg•m ² | 2.11 × 10 ⁻⁴ kg•m ² | |
| Power rate | 15.7 kW/s | 19.4 kW/s | 46.8 kW/s | 26.9 kW/s | |
| Allowable radial load | 78 N | 245 N | 245 N | 392 N | |
| Allowable thrust load | 49 N | 68 N | 68 N | 147 N | |
| Weight (with brake -BS1) | 0.9 kg | 1.9 kg | 2.6 kg | 5.7 kg | |
| Applicable servo driver | R7D-AP01H/L | R7D-AP02H/L | R7D-AP04H/L | R7D-AP08H | |
| Encoder resolution | 2,000 pulses/revolution for phase-A and phase-B, 1 pulse/revolution for phase-Z | | | | |
| Radiation shield dimensions | t6 x250 mm square | | | t12 x300 mm square | |
| Brake specifications | Brake inertia | 3.1 × 10 ⁻⁶ kg•m ² | 1.52 × 10 ⁻⁵ kg•m ² | 1.52 × 10 ⁻⁵ kg•m ² | 8.75 × 10 ⁻⁵ kg•m ² |
| | Excitation voltage | 24 V DC ±10% | | | |
| | Power consumption (at 20° C) | 6 W | 5 W | 7.6 W | 7.5 W |
| | Current consumption (at 20° C) | 0.25 A | 0.21 A | 0.32 A | 0.31 A |
| | Static friction torque | 0.4 N•m min. | 0.9 N•m min. | 1.9 N•m min. | 3.5 N•m min. |
| | Attraction time | 40 ms max. | 40 ms max. | 40 ms max. | 40 ms max. |
| | Release time | 20 ms max. | 20 ms max. | 20 ms max. | 20 ms max. |
| | Backlash | 1° | 1° | 1° | 1° |
| | Rating | Continuous | | | |
| Insulation grade | Type F | | | | |

Cylindrical Servo Motors without Brakes

| Item | R7M-A03030-S1 | R7M-A05030-S1 | R7M-A10030-S1 | R7M-A20030-S1 | R7M-A40030-S1 | R7M-A75030-S1 |
|----------------------------------|---|--|--|---|---|---|
| Rated output | 30 W | 50 W | 100 W | 200 W | 400 W | 750 W |
| Rated torque | 0.095 N•m | 0.159 N•m | 0.318 N•m | 0.637 N•m | 1.27 N•m | 2.39 N•m |
| Rated rotation speed | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. |
| Momentary maximum rotation speed | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. |
| Momentary maximum torque | 0.29 N•m | 0.48 N•m | 0.96 N•m | 1.91 N•m | 3.82 N•m | 7.1 N•m |
| Rated current (rms) | 0.42 A | 0.6 A | 0.87 A | 2.0 A | 2.6 A | 4.4 A |
| Momentary maximum current (rms) | 1.3 A | 1.9 A | 2.8 A | 6.0 A | 8.0 A | 13.9 A |
| Rotor inertia | $1.7 \times 10^{-6} \text{ kg}\cdot\text{m}^2$ | $2.2 \times 10^{-6} \text{ kg}\cdot\text{m}^2$ | $3.6 \times 10^{-6} \text{ kg}\cdot\text{m}^2$ | $1.19 \times 10^{-5} \text{ kg}\cdot\text{m}^2$ | $1.87 \times 10^{-5} \text{ kg}\cdot\text{m}^2$ | $6.67 \times 10^{-5} \text{ kg}\cdot\text{m}^2$ |
| Power rate | 5.31 kW/s | 11.5 kW/s | 28.1 kW/s | 34.1 kW/s | 86.3 kW/s | 85.6 kW/s |
| Allowable radial load | 68 N | 68 N | 78 N | 245 N | 245 N | 392 N |
| Allowable thrust load | 54 N | 54 N | 54 N | 74 N | 74 N | 147 N |
| Weight without brake | 0.3 kg | 0.4 kg | 0.5 kg | 1.1 kg | 1.7 kg | 3.4 kg |
| Applicable servo driver | R7D-APA3H | R7D-APA5H | R7D-AP01H | R7D-AP02H | R7D-AP04H | R7D-AP08H |
| Encoder resolution | 2,000 pulses/revolution for phase-A and phase-B, 1 pulse/revolution for phase-Z | | | | | |
| Radiation shield dimensions | t6× 250 mm square | | | | | |

Cylindrical Servo Motors with Brakes

| Item | R7M-A03030-BS1 | R7M-A05030-BS1 | R7M-A10030-BS1 | R7M-A20030-BS1 | R7M-A40030-BS1 | R7M-A75030-BS1 | |
|----------------------------------|---|---|---|---|---|---|--|
| Rated output | 30 W | 50 W | 100 W | 200 W | 400 W | 750 W | |
| Rated torque | 0.095 N•m | 0.159 N•m | 0.318 N•m | 0.637 N•m | 1.27 N•m | 2.39 N•m | |
| Rated rotation speed | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. | 3,000 r/min. | |
| Momentary maximum rotation speed | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. | 4,500 r/min. | |
| Momentary maximum torque | 0.29 N•m | 0.48 N•m | 0.96 N•m | 1.91 N•m | 3.82 N•m | 7.1 N•m | |
| Rated current (rms) | 0.42 A | 0.6 A | 0.87 A | 2.0 A | 2.6 A | 4.4 A | |
| Momentary maximum current (rms) | 1.3 A | 1.9 A | 2.8 A | 6.0 A | 8.0 A | 13.9 A | |
| Rotor inertia | $1.7 \times 10^{-6} \text{ kg}\cdot\text{m}^2$ | $2.2 \times 10^{-6} \text{ kg}\cdot\text{m}^2$ | $3.6 \times 10^{-6} \text{ kg}\cdot\text{m}^2$ | $1.19 \times 10^{-5} \text{ kg}\cdot\text{m}^2$ | $1.87 \times 10^{-5} \text{ kg}\cdot\text{m}^2$ | $6.67 \times 10^{-5} \text{ kg}\cdot\text{m}^2$ | |
| Power rate | 5.31 kW/s | 11.5 kW/s | 28.1 kW/s | 34.1 kW/s | 86.3 kW/s | 85.6 kW/s | |
| Allowable radial load | 68 N | 68 N | 78 N | 245 N | 245 N | 392 N | |
| Allowable thrust load | 54 N | 54 N | 54 N | 74 N | 74 N | 147 N | |
| Weight with brake | 0.6 kg | 0.7 kg | 0.8 kg | 1.6 kg | 2.2 kg | 4.3 kg | |
| Applicable servo driver | R7D-APA3H | R7D-APA5H | R7D-AP01H | R7D-AP02H | R7D-AP04H | R7D-AP08H | |
| Encoder resolution | 2,000 pulses/revolution for phase-A and phase-B, 1 pulse/revolution for phase-Z | | | | | | |
| Radiation shield dimensions | t6× 250 mm square | | | | | | |
| Brake specifications | Brake inertia | $0.85 \times 10^{-6} \text{ kg}\cdot\text{m}^2$ | $0.85 \times 10^{-6} \text{ kg}\cdot\text{m}^2$ | $0.85 \times 10^{-6} \text{ kg}\cdot\text{m}^2$ | $6.4 \times 10^{-6} \text{ kg}\cdot\text{m}^2$ | $6.4 \times 10^{-6} \text{ kg}\cdot\text{m}^2$ | $1.7 \times 10^{-5} \text{ kg}\cdot\text{m}^2$ |
| | Excitation voltage | 24 V DC ±10% V | | | | | |
| | Power consumption (at 20° C) | 6 W | 6 W | 6 W | 7 W | 7 W | 7.7 W |
| | Current consumption (at 20° C) | 0.25 A | 0.25 A | 0.25 A | 0.29 A | 0.29 A | 0.32 A |
| | Static friction torque | 0.2 N•m min. | 0.2 N•m min. | 0.34 N•m min. | 1.47 N•m min. | 1.47 N•m min. | 2.45 N•m min. |
| | Attraction time | 30 ms max. | 30 ms max. | 30 ms max. | 60 ms max. | 60 ms max. | 60 ms max. |
| | Release time | 60 ms max. | 60 ms max. | 60 ms max. | 20 ms max. | 20 ms max. | 20 ms max. |
| | Backlash | 1° | 1° | 1° | 1° | 1° | 1° |
| | Rating | Continuous | Continuous | Continuous | Continuous | Continuous | Continuous |
| Insulation grade | Type F | Type F | Type F | Type F | Type F | Type F | |

Dimensions

Servo Drives Dimensions (mm)

| Input voltage | Rating | Drive model | H | W | D |
|------------------------------|--------|-------------|-----|----|-----|
| 1-phase, 100 VAC and 200 VAC | 30 W | R7D-APA3H/L | 160 | 55 | 130 |
| | 50 W | R7D-APA5H/L | 160 | 55 | 130 |
| | 100 W | R7D-AP01H/L | 160 | 55 | 130 |
| | 200 W | R7D-AP02H/L | 160 | 55 | 130 |
| | 400 W | R7D-AP04H/L | 160 | 75 | 130 |
| 1-phase, 200 VAC | 750 W | R7D-AP08H | 160 | 90 | 180 |

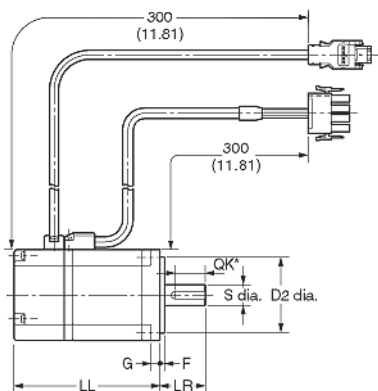
Cylindrical Servo Motors (3,000 r/min) Dimensions (mm)

200 VAC: 30 W/50 W/100 W/200 W/400 W/750 W

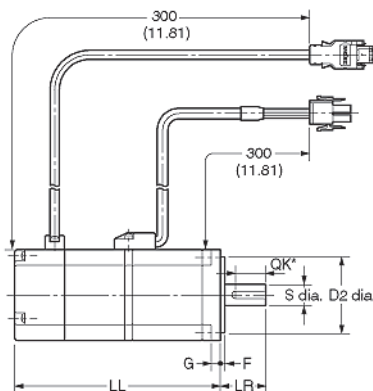
Without brake: R7M-A03030-S1-D/A05030-S1-D/A10030-S1-D/A20030-S1-D/A40030-S1-D/A75030-S1-D

With brake: R7M-A03030-BS1-D/A05030-BS1-D/A10030-BS1-D/A20030-BS1-D/A40030-BS1-D/A75030-BS1-D

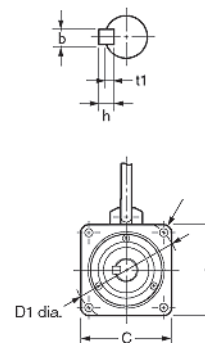
R7M-A□□□30(-S1) (Without Brake)



R7M-A□□□30(-S1) (With Brake)



*Axis End Dimensions



| Model | Overall length | | Flange surface | | | Axis end | | | | | | | |
|----------------|----------------|----|----------------|----|------|----------|---|----------------|------|----|---|---|-----|
| | LL | LR | C | D1 | D2 | F | G | Z | S | QK | b | h | t1 |
| R7M-A03030-S1 | 69.5 | 25 | 40 | 46 | 30h7 | 2.5 | 5 | Two, 4.3 dia. | 6h6 | 14 | 2 | 2 | 1.2 |
| R7M-A03030-BS1 | 101 | 25 | 40 | 46 | 30h7 | 2.5 | 5 | Two, 4.3 dia. | 6h6 | 14 | 2 | 2 | 1.2 |
| R7M-A05030-S1 | 77 | 25 | 40 | 46 | 30h7 | 2.5 | 5 | Two, 4.3 dia. | 6h6 | 14 | 2 | 2 | 1.2 |
| R7M-A05030-BS1 | 108.5 | 25 | 40 | 46 | 30h7 | 2.5 | 5 | Two, 4.3 dia. | 6h6 | 14 | 2 | 2 | 1.2 |
| R7M-A10030-S1 | 94.5 | 25 | 40 | 46 | 30h7 | 2.5 | 5 | Two, 4.3 dia. | 8h6 | 14 | 3 | 3 | 1.8 |
| R7M-A10030-BS1 | 135 | 25 | 40 | 46 | 30h7 | 2.5 | 5 | Two, 4.3 dia. | 8h6 | 14 | 3 | 3 | 1.8 |
| R7M-A20030-S1 | 96.5 | 30 | 60 | 70 | 50h7 | 3 | 6 | Four, 5.5 dia. | 14h6 | 20 | 5 | 5 | 3 |
| R7M-A20030-BS1 | 136 | 30 | 60 | 70 | 50h7 | 3 | 6 | Four, 5.5 dia. | 14h6 | 20 | 5 | 5 | 3 |
| R7M-A40030-S1 | 124.5 | 30 | 60 | 70 | 50h7 | 3 | 6 | Four, 5.5 dia. | 14h6 | 20 | 5 | 5 | 3 |
| R7M-A40030-BS1 | 164 | 30 | 60 | 70 | 50h7 | 3 | 6 | Four, 5.5 dia. | 14h6 | 20 | 5 | 5 | 3 |
| R7M-A75030-S1 | 145 | 40 | 80 | 90 | 70h7 | 3 | 8 | Four, 7 dia. | 16h6 | 30 | 5 | 5 | 3 |
| R7M-A75030-BS1 | 189.5 | 40 | 80 | 90 | 70h7 | 3 | 8 | Four, 7 dia. | 16h6 | 30 | 5 | 5 | 3 |

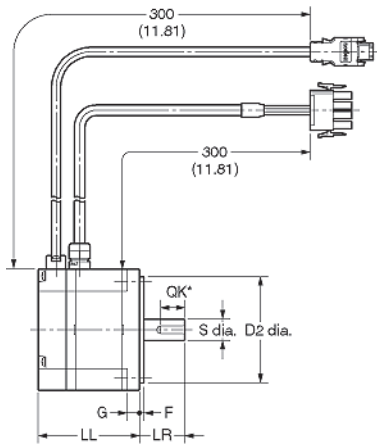
Flat Servo Motors (3,000 r/min) Dimensions (mm)

200 VAC: 100 W/200 W/400 W/750 W

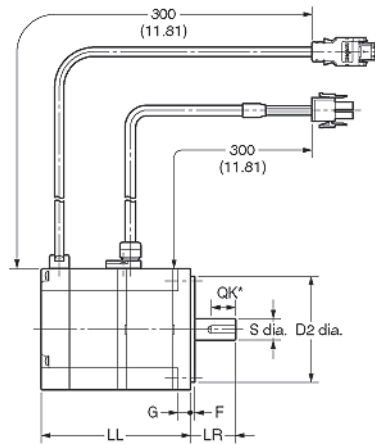
Without brake: R7M-AP10030-S1-D/AP20030-S1-D/AP40030-S1-D/AP75030-S1-D

With brake: R7M-AP10030-BS1-D/AP20030-BS1-D/AP40030-BS1-D/AP75030-BS1-D

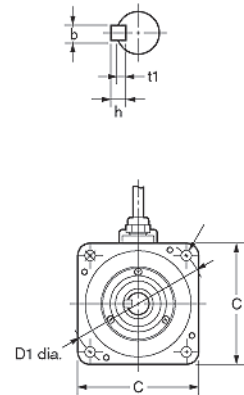
R7M-AP□□□30(-S1) (Without Brake)



R7M-AP□□□30(-S1) (With Brake)



*Axis End Dimensions



| Model | Overall length | | Flange surface | | | Axis end | | | | | | | |
|-----------------|----------------|----|----------------|-----|-------|----------|----|----------|------|----|---|---|-----|
| | LL | LR | C | D1 | D2 | F | G | Z | S | QK | b | h | t1 |
| R7M-AP10030-S1 | 62 | 25 | 60 | 70 | 50h7 | 2.5 | 6 | 5.5 dia. | 8h6 | 14 | 3 | 3 | 1.8 |
| R7M-AP10030-BS1 | 91 | 25 | 60 | 70 | 50h7 | 2.5 | 6 | 5.5 dia. | 8h6 | 14 | 3 | 3 | 1.8 |
| R7M-AP20030-S1 | 67 | 30 | 80 | 90 | 70h7 | 3 | 8 | 7 dia. | 14h6 | 16 | 5 | 5 | 3 |
| R7M-AP20030-BS1 | 98.5 | 30 | 80 | 90 | 70h7 | 3 | 8 | 7 dia. | 14h6 | 16 | 5 | 5 | 3 |
| R7M-AP40030-S1 | 87 | 30 | 80 | 90 | 70h7 | 3 | 8 | 7 dia. | 14h6 | 16 | 5 | 5 | 3 |
| R7M-AP40030-BS1 | 118.5 | 30 | 80 | 90 | 70h7 | 3 | 8 | 7 dia. | 14h6 | 16 | 5 | 5 | 3 |
| R7M-AP75030-S1 | 86.5 | 40 | 120 | 145 | 110h7 | 3.5 | 10 | 10 dia. | 16h6 | 22 | 5 | 5 | 3 |
| R7M-AP75030-BS1 | 120 | 40 | 120 | 145 | 110h7 | 3.5 | 10 | 10 dia. | 16h6 | 22 | 5 | 5 | 3 |